CONTACTS IN TOTALLY SEPARABLE PACKINGS IN THE PLANE AND IN HIGH DIMENSIONS*

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ABSTRACT. We study the contact structure of totally separable packings of translates of a convex body K in \mathbb{R}^d , that is, packings where any two translates of the packing have a separating hyperplane that does not intersect the interior of any translate in the packing. The separable Hadwiger number $H_{\text{sep}}(K)$ of K is defined to be the maximum number of translates touched by a single translate, with the maximum taken over all totally separable packings of translates of K. We show that for each $d \geq 8$, there exists a smooth and strictly convex K in \mathbb{R}^d with $H_{\text{sep}}(K) > 2d$, and asymptotically, $H_{\text{sep}}(K) = \Omega((3/\sqrt{8})^d)$.

We show that Alon's packing of Euclidean unit balls such that each translate touches at least $2^{\sqrt{d}}$ others whenever d is a power of 4, can be adapted to give a totally separable packing of translates of the ℓ_1 -unit ball with the same touching property.

We also consider the maximum number of touching pairs in a totally separable packing of n translates of any planar convex body K. We prove that the maximum equals $\lfloor 2n-2\sqrt{n} \rfloor$ if and only if K is a quasi hexagon, thus completing the determination of this value for all planar convex bodies.

1 Introduction

We define a translative packing of a convex body K in \mathbb{R}^d to be a collection $\{x_1 + K, x_2 + K, \ldots, x_n + K\}$ of translates of K such that no two translates have interior points in common. We say that two such translates touch if they have a common boundary point. A packing is totally separable if any two bodies in the packing have a separating hyperplane that does not intersect the interior of any translate in the packing. The contact graph of the packing is the graph defined on the set of translates in the packing where two translates are joined by an edge if they touch.

In this paper, we study the maximum and minimum degrees, and the number of edges of contact graphs of totally separable packings of a convex body.



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The separable Hadwiger number, denoted as $H_{\text{sep}}(K)$, of a convex body K in \mathbb{R}^d is the maximum degree in the contact graph of any totally separable packing of K.

This number is known for the d-cube $[0,1]^d$. Any contact graph of a translative packing of the d-cube can be embedded in the contact graph of a \mathbb{Z}^d -lattice packing of the cubes (Fejes Tóth and Sauer [FTS77]), which is clearly totally separable. Therefore, the maximum possible degree equals the Hadwiger number of the d-cube, which is $3^d - 1$. It is also known that the maximum possible minimum degree equals $(3^d - 1)/2$ (Talata [Tal11]).

For arbitrary K we have the well-known bounds $2d \leq H_{\text{sep}}(K) \leq 3^d - 1$. If K is smooth or strictly convex and $d \leq 4$, then $H_{\text{sep}}(K) = 2d$ [BN18]. In contrast, we show that for all $d \geq 8$ there exists a smooth and strictly convex body K in \mathbb{R}^d with $H_{\text{sep}}(K) > 2d$.

Theorem 1. For each $d \ge 8$ there exists a d-dimensional smooth and strictly convex body with a separable Hadwiger number of at least 2d + 2. For d = 9, 10, 11, 12, 14, there is a lower bound of 29, 39, 50, 65, 91, respectively.

These lower bounds are obtained from the existence of certain spherical codes, obtained by Conway–Hardin–Sloane [CHS96].

We find some upper bounds for dimensions 5, 6, and 7.

Proposition 2. The separable Hadwiger number of a 5, 6, 7-dimensional smooth and strictly convex body is at most 15, 27, 63, respectively.

For large d we have an exponential lower bound.

Theorem 3. There exists a d-dimensional smooth and strictly convex body with a separable Hadwiger number of at least $\Omega((3/\sqrt{8})^d)$.

We show that the ℓ_1 ball has a totally separable packing with high minimum degree in the contact graph.

Theorem 4. There exists a finite totally separable packing of ℓ_1^d -unit balls such that each ball touches at least $2^{\sqrt{d}}$ others, when d is a power of 4.

The number of edges in the contact graph of a packing, that is, the number of touching pairs is called the *contact number* of the packing. For a positive integer n, we denote the largest contact number of a totally separable packing of n translates of a convex body K by $c_{\text{sep}}(K,n)$. The *central symmetral* of K is the o-symmetric convex body (1/2)(K-K). For later reference, we state the following well-known lemma.

Lemma 5. For any convex body K in \mathbb{R}^d , $\{x_1 + K, x_2 + K, \dots, x_n + K\}$ is a separable packing if and only if $\{x_1 + C, x_2 + C, \dots, x_n + C\}$ is a separable packing, where C is the central symmetral of K. Moreover, in this case, the contact graphs of the two packings are isomorphic.

The following class of convex bodies in the plane turns out to be special from the point of view of totally separable packings. We call a planar convex body K a quasi hexagon

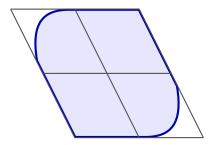


Figure 1: An o-symmetric quasi hexagon

if there exists a parallelogram P containing K such that some two opposite vertices of P lie on the boundary of K, and such that each edge of P has a translate contained in K. Examples of quasi hexagons are triangles, parallelograms, affine regular hexagons, as well as a quarter circle.

Lemma 6. Let K be a convex disc. Then K is a quasi hexagon if and only if its central symmetral is a quasi hexagon. Furthermore, an o-symmetric K is a quasi hexagon if it contains two line segments on its boundary with a common endpoint, such that both are of at least unit length in the norm with unit ball K (Figure 1).

Proof. The only statement that might not be straightforward is that if the central symmetral C of K is a quasi hexagon, then so is K. Thus, assume that C is a quasi hexagon, and let P denote the parallelogram in the definition of a quasi hexagon. With a translation, one may assume that $K \subseteq P$. Clearly, K contains the vertices of P contained in C. Let e and e' be one pair of parallel edges of P, and f and f' be the other. On the one hand, we have length $(C \cap e) = [\operatorname{length}(K \cap e) + \operatorname{length}(K \cap e')]/2$. On the other hand, since C is a quasi hexagon, length $(C \cap e) \ge \operatorname{length}(e)/2$. It now follows that a translate of f is contained in K. The same holds for e and thus, K is a quasi hexagon.

Lemmas 5 and 6 enable us to consider only o-symmetric convex bodies in our proofs. For other characterizations of o-symmetric quasi hexagons, see Lemmas 14 and 15. Our main result in the plane is the following upper bound for $c_{\text{sep}}(K, n)$ if K is not a quasi hexagon.

Theorem 7. Let K be a convex body on the plane. If K is not a quasi hexagon, then $c_{\text{sep}}(K,n) \leq |2n-2\sqrt{n}|$.

The special case when K is the Euclidean disc was solved by Bezdek, Szalkai and Szalkai [BSS16] using Harborth's method [Har74]. This result was extended to smooth and strictly convex bodies by Bezdek, Khan and Oliwa [BKO19] using a type of angular measure called B-measures. However, there are many planar norms without B-measures [NPS20], and we follow an approach avoiding them entirely. As a corollary, the exact values of $c_{\rm sep}(K,n)$ are now known for every planar convex body K.

Corollary 8. Let K be a convex body in the plane.

- 1. If K is a parallelogram, then $c_{\text{sep}}(K,n) = |4n \sqrt{28n 12}|$.
- 2. If K is a quasi hexagon but not a parallelogram, then $c_{sep}(K,n) = |3n \sqrt{12n 3}|$.
- 3. If K is not a quasi hexagon, then $c_{sep}(K,n) = \lfloor 2n 2\sqrt{n} \rfloor$.

The upper bounds in the first two claims above follow directly from Brass' results in [Bra96], while the lower bounds in all three claims follow from suitable lattice packings (Figure 5).

As pointed out in [BKO19, Remark 14], the proof of the lower bound $c_{\text{sep}}(K, n) \ge \lfloor 2n - 2\sqrt{n} \rfloor$ does not make use of smoothness. In fact, it relies only on the existence of a parallelogram P containing K with the property that the midpoints of the edges of P are in K. Any parallelogram that contains K and of minimum area has this property. It then remains to observe that the maximum number of pairs of cells that touch in an edge in a polyomino of n cells is $\lfloor 2n - 2\sqrt{n} \rfloor$ [BKO19].

We prove Theorems 1, 3 and 4 and Proposition 2 in Section 2, and Theorem 7 in Sections 3 and 4. We conclude with some open problems in Section 5.

2 Many contacts in dimension d

To prove Theorems 1 and 3, we use the following result from [BN18] to find smooth and strictly convex bodies with large separable Hadwiger number.

Lemma 9 ([BN18, Lemma 2.1 and Note 2.2]). There exists an o-symmetric, smooth and strictly convex body in \mathbb{R}^d with $H_{\text{sep}}(K) \geq n$ if, and only if, there exist vectors $x_1, x_2, \ldots, x_n \in \mathbb{R}^d$ and linear functionals $\varphi_1, \varphi_2, \ldots, \varphi_n \in (\mathbb{R}^d)^*$ such that for all distinct i, j,

•
$$\varphi_i(x_i) = 1$$
 and $-1 \le \varphi_i(x_j) \le 0$, and

•
$$\varphi_i(x_i) > -1$$
 whenever $x_i \neq -x_i$ or $\varphi_i \neq -\varphi_i$.

Proposition 10. Let $\alpha < 1$ and suppose that there exist Euclidean unit vectors $v_1, \ldots, v_m \in \mathbb{R}^{d-1}$ such that $\langle v_i, v_j \rangle \in (-1 + 2\alpha, \alpha]$ for any distinct i, j. Then for each $k \geq 0$ there exists a smooth and strictly convex body in \mathbb{R}^{d+k} with a totally separable Hadwiger number of at least m + 2k.

Proof. For each i = 1, ..., m, let $x_i = (v_i, 1, o) \in \mathbb{R}^{d-1} \oplus \mathbb{R} \oplus \mathbb{R}^k = \mathbb{R}^{d+k}$ and

$$\varphi_i = \frac{1}{1-\alpha}(v_i, -\alpha, o) \in \left(\mathbb{R}^{d-1}\right)^* \oplus \mathbb{R}^* \oplus (\mathbb{R}^k)^* = \left(\mathbb{R}^{d+k}\right)^*,$$

and for each $j=1,\ldots,k$, let $x_{m+j}=(o,0,e_j)$ and $\varphi_{m+j}=(o,0,e_j^*)$, where $\{e_1,\ldots,e_k\}$ and $\{e_1^*,\ldots,e_k^*\}$ are the standard orthonormal bases of \mathbb{R}^k and $(\mathbb{R}^k)^*$. Then $\varphi_i(x_i)=1$ and $\varphi_i(x_j)=\frac{\langle v_i,v_j\rangle-\alpha}{1-\alpha}\in(-1,0]$ for all distinct $i,j\leq m$, and if i>m or j>m then

$$\varphi_i(x_j) = \begin{cases} 1 & \iff i = j, \\ -1 & \iff i, j > m \text{ and } |i - j| = d, \\ 0 & \text{otherwise.} \end{cases}$$

It then follows from Lemma 9 that there exists a smooth and strictly convex body $K \subseteq \mathbb{R}^d$ such that $\{x + K \mid x = o \text{ or } x = x_i \text{ for some } i\}$ is a totally separable packing of m + 1 translates of K with all $x_i + K$ touching K.

Proof of Theorem 1. There exist 18 unit vectors in \mathbb{R}^7 with pairwise inner products in the interval (-1/3, 1/3) (Conway, Hardin, Sloane [CHS96]). This, together with Proposition 10, gives the existence of a smooth and strictly convex K in \mathbb{R}^d with $H_{\text{sep}}(K) \geq 2d + 2$ for each $d \geq 8$. Similarly, for the other claims we observe from [CHS96] that there exist 29, 39, 50, 65, 91 such unit vectors in $\mathbb{R}^8, \mathbb{R}^9, \mathbb{R}^{10}, \mathbb{R}^{11}, \mathbb{R}^{13}$, respectively.

Proof of Theorem 3. By Proposition 10, it is sufficient to find Euclidean unit vectors with pairwise inner products in (-1/3,1/3). It is well known that there exist $\Omega((3/\sqrt{8})^d)$ such unit vectors. Here we give the short proof using the deletion method. Choose k vectors x_1, \ldots, x_k independently from the unit ball of \mathbb{R}^d . For any two x_i and x_j of them, the probability that $||x_i - x_j||_2 \le 2/\sqrt{3}$ is at most $(\sqrt{8}/3)^d =: p$. Similarly, the probability that $||x_i + x_j||_2 \le 2/\sqrt{3}$ is at most p. Thus the expected number of pairs $\{x_i, x_j\}$ such that $||x_i - x_j||_2 \le 2/\sqrt{3}$ or $||x_i + x_j||_2 \le 2/\sqrt{3}$ is at most $2p\binom{k}{2}$ by the union bound. It follows that there exist x_1, \ldots, x_k from the unit ball such that less than pk^2 pairs satisfy $||x_i \pm x_j||_2 \le 2/\sqrt{3}$. For each one of these pairs of vectors, remove one of them. There remains at least $k - pk^2$ vectors such that for any pair x_i and x_j we have $||x_i \pm x_j||_2 > 2/\sqrt{3}$. If we normalise each x_i , we obtain at least $k - pk^2$ unit vectors such that all pairwise inner product are in (-1/3, 1/3). This is maximised by choosing k = 1/(2p), which proves the theorem.

To prove Proposition 2, we need the following counterpart to Proposition 10.

Proposition 11. If there exists a d-dimensional smooth and strictly convex K with separable Hadwiger number of at least n, then for some integer $k \geq 0$ there exists an $(n-2k) \times (n-2k)$ matrix $[a_{ij}]$ of rank at most d-k+1 and satisfying $a_{ii}=1$ for all $i=1,\ldots,n-2k$, and $-1/3 < a_{ij} < 1/3$ for all distinct i,j.

Proof. We may assume that K is o-symmetric. Consider the vectors $x_i \in \mathbb{R}^d$ and functionals $\varphi_i \in (\mathbb{R}^d)^*$, $i = 1, \dots n$ given by Lemma 9. Whenever there exist distinct i, j such that $\varphi_i(x_j) = -1$, we must have $x_i = -x_j$ and $\varphi_i = -\varphi_j$. It follows that $\varphi_i(x_k) = 0$ for all $k \neq i, j$, and thus we can remove $x_i, x_j, \varphi_i, \varphi_j$ and move one dimension down. We repeat this k times until $-1 < \varphi_i(x_j)$ for all distinct i, j, and then $[\varphi_i(x_j)]_{i,j}$ is an $(n-2k) \times (n-2k)$ matrix $[a_{ij}]$ of rank at most d-k, with 1s on the diagonal and all other entries in the interval (-1,0]. Choose $\varepsilon \in (0,1)$ sufficiently small such that $-1+\varepsilon \leq \varphi_i(x_j)$ whenever $i \neq j$. If we set $a_{ij} = ((2+\varepsilon)\varphi_i(x_j)+1-\varepsilon)/3$, then $[a_{ij}]$ is the desired matrix.

We recall a well-known result on the rank of a square matrix in terms of its trace and Frobenius norm.

Lemma 12 (Rank Lemma). The rank r of a real non-zero square matrix $A = [a_{ij}]$ satisfies $r \ge (\sum_i a_{ii})^2 / \sum_{i,j} a_{ij}^2$.

Proof of Proposition 2. Assume there is a smooth and strictly convex body with separable Hadwiger number n in \mathbb{R}^d with d=5,6 or 7. Let A be the $m \times m$ matrix, m=n-2k, of rank $r \leq d-k+1$ from Proposition 11. Now, the Rank Lemma yields

$$d-k+1 \ge r > \frac{m^2}{m+(m^2-m)/9} = \frac{9m}{m+8},$$

hence $n < \frac{8(d-k+1)}{8-d+k} + 2k$. It can be checked that this last expression is maximised when k=0 since $d \geq 4$. Thus, $n < \frac{8(d+1)}{8-d}$, and Proposition 2 follows.

Next, we turn to the proof of Theorem 4. Alon [Alo97] uses a Reed–Solomon code to construct a packing of unit Euclidean balls in \mathbb{R}^d such that each ball touches at least $2^{\sqrt{d}}$ others when $d=4^k$ for some $k\in\mathbb{N}$. This code $C\subseteq\{0,1\}^d$ has the property that any two points in C have Hamming distance at least some fixed D, and for any point in C, there are at least $2^{\sqrt{d}}$ points of C at Hamming distance D. It is easily seen that using the same code, this construction yields a translative packing for any unconditional convex body (symmetric with respect to all the d coordinate hyperplanes), for instance the ℓ_p^d -unit balls. In the next proposition, we show that for ℓ_1^d -unit balls this construction gives a totally separable packing. This implies Theorem 4.

Proposition 13. Let $C \subseteq \{0,1\}^d$ be such that any two vectors from C have Hamming distance at least D. Then the packing of ℓ_1^d balls of radius D/2 with centres from C is totally separable.

Proof. We show the stronger property that for any $u \in C$, the ℓ_1^d -ball with centre u and radius D/2 has a supporting hyperplane H such that all ℓ_1^d -balls with centres from $C \setminus \{u\}$ and radius D/2 lie in the closed half-space bounded by H on the opposite side of u.

Define the linear functional $f = 2u - (1, 1, ..., 1) \in (\ell_1^d)^* = \ell_\infty^d$. Then $||f||_\infty = 1$ and f(u) equals the number of 1s in the coordinates of u.

Next consider any $u' \in C \setminus \{u\}$. For each $i, j \in \{0, 1\}$, let m_{ij} denote the number of coordinates $t \in \{1, \ldots, d\}$ where $u_t = i$ and $u'_t = j$. Then the Hamming distance between u and u' is $m_{01} + m_{10} \geq D$, $f(u) = m_{10} + m_{11}$, and $f(u') = m_{11} - m_{01}$. It follows that $f(u) - f(u') = m_{01} + m_{10} \geq D$, and since $||f||_{\infty} = 1$, the hyperplane $H = \{x \in \mathbb{R}^d \mid f(x) = f(u) - D/2\}$ separates the ℓ_1^d balls around u and u' of radius D/2. Indeed, for any $x \in \ell_1^d$ satisfying $||x - u||_1 \leq D/2$ we have $f(x - u) \geq -D/2$, hence $f(x) \geq f(u) - D/2$, and for any $x \in \ell_1^d$ satisfying $||x - u'||_1 \leq D/2$ we have $D/2 \geq f(x - u') = f(x) - f(u) + f(u) - f(u') \geq f(x) - f(u) + D$, hence $f(x) \leq f(u) - D/2$.

3 Preliminaries on planar packings and angular measures

It will be helpful to note that o-symmetric quasi hexagons are those o-symmetric planar convex bodies that have an affine position between a certain affine regular hexagon and a square, in the following sense. We leave the proof to the reader.

Lemma 14. An o-symmetric convex body K in \mathbb{R}^2 is a quasi hexagon if and only if there is a linear $T \colon \mathbb{R}^2 \to \mathbb{R}^2$ such that $H \subseteq T(K) \subseteq S$, where $H = \text{conv}\{(\pm 1, 0), (0, \pm 1), \pm (1, 1)\}$ and $S = [-1, 1]^2$.

Lemma 15. Let K be an o-symmetric convex body. Let $u_1, u_2 \in \operatorname{bd} K$ be such that $\{K, K + 2u_1, K + 2u_2\}$ is a totally separable packing in which any two of the translates touch. Then K is a quasi hexagon.

Proof. By possibly relabelling the three translates, we can assume that there exist two intersecting lines ℓ_1 and ℓ_2 such that K and $K + 2u_i$ are on opposite sides of ℓ_i , and K and $K + 2u_{1-i}$ are on the same side of ℓ_i (i = 1, 2). Since $K + 2u_1$ and $K + 2u_2$ are separated by both ℓ_1 and ℓ_2 , it follows that the intersection point of the two lines equals $u_1 + u_2$, and that bd K contains the segments $[u_1, u_1 + u_2]$ and $[u_2, u_1 + u_2]$. Thus, K is a quasi hexagon. \square

The contact graph of a totally separable packing of translates of K is planar, as long as K is not a parallelogram [Bra96]. Moreover, Lemma 15 implies that the contact graph is triangle-free if K is not a quasi hexagon. This already gives that the number of edges in a contact graph is at most 2n-4. In the next section, we improve this bound to $2n-2\sqrt{n}$ with the use of a certain angular measure, which we now introduce.

Definition 16. Let K be an o-symmetric convex body on the plane. For two points p, q on $\operatorname{bd} K$, we denote the *clockwise arc* of $\operatorname{bd} K$ connecting p and q by \widehat{pq} . If $p \neq -q$, then we denote the *minor arc* connecting p and q by $\widehat{pq} = \widehat{qp}$.

Definition 17. Let K be an o-symmetric convex body on the plane. A Borel measure μ on bd K is an angular measure if

- 1. $\mu(\text{bd }K) = 2\pi$,
- 2. $\mu(X) = \mu(-X)$ for every Borel subset X of bd K, and
- 3. μ is continuous, that is, $\mu(\{p\}) = 0$ for every $p \in \mathrm{bd} K$.

We note that the angular measure of any arc connecting two opposite points of bd K (ie., a semicircle) equals π . It follows that for any angular measure, the sum of the interior angles of a triangle equals π . This can be shown in exactly the same way as the proof for the Euclidean angular measure. It then follows by triangulation (see [Bra96]) that for any simple closed polygon with v vertices,

the sum of the interior angles
$$= (v-2)\pi$$
. (1)

An o-symmetric convex body K has many angular measures. For example, we can take the Euclidean angular measure after choosing a Euclidean structure on the plane, or we can take the one-dimensional Hausdorff measure on bd K, normalized to 2π . Most of these angular measures have no further interesting properties beyond (1), and where angular measures have been used in the literature, specific ones with further properties have been constructed. Brass [Bra96] constructed an angular measure in which the angles of any equilateral triangle

are all $\pi/3$. In [BKO19] the notion of a *B-measure* is used. This is an angular measure μ such that $\mu(A) = \pi/2$ whenever A is an arc on bd K with endpoints a and b, say, such that a is *Birkhoff orthogonal* to b, that is, the line through a in the direction b supports K at a. It turns out that B-measures exist only in very special cases [NPS20]. In [BKO19], Theorem 7 is proved for all smooth and strictly convex bodies by approximating these bodies with bodies admitting a B-measure. We avoid the need for approximation by using the following type of angular measure that exists for any K that is not a quasi hexagon.

Definition 18. Let K be an o-symmetric convex body in the plane that is not a quasi hexagon. A π -measure is an angular measure μ on $\operatorname{bd} K$ if for every segment $[a,b] \subset \operatorname{bd} K$ with $\|a-b\|_K > 1$ we have

- 1. $\mu(\widehat{bc}) = 0$ where $c \in [a, b]$ is such that $||a c||_K = 1$, and $\mu(\widehat{ad}) = 0$ where $d \in [a, b]$ is such that $||b d||_K = 1$,
- 2. $\mu(\widehat{ae}) = 0$ for any segment $[a, e] \subset \operatorname{bd} K$ not parallel to [a, b], and $\mu(\widehat{fb}) = 0$ for any segment $[f, b] \subset \operatorname{bd} K$ not parallel to [a, b].

Any segment [a, e] or [f, b] in the above definition will have K-length strictly smaller than 1, since K is not a quasi hexagon. It is easy to see that any K that is not a quasi hexagon admits a π -measure, since after removing the arcs that are required to have measure 0 from bd K, there will always be some arcs left on which a mass of 2π can be distributed. The following property of π -measures will be crucial for the proof of Theorem 7.

Lemma 19. Let K be an o-symmetric convex body that is not a quasi hexagon, and let μ be a π -measure on $\operatorname{bd} K$. Let $u_0, u_1, u_2 \in \operatorname{bd} K$ be such that u_1 is on the directed arc $\widehat{u_2u_0}$ and either $\{K, K + 2u_0, K + 2u_1, K + 2u_2\}$ or $\{K, K + 2u_0, K + 2u_1, K + 2(u_1 - u_2)\}$ is a totally separable packing. Then $\mu(\widehat{u_2u_0}) \geq \pi$.

Proof. We first consider the totally separable packing $\{K, K+2u_0, K+2u_1, K+2u_2\}$. Let ℓ_i be a line separating K and $K+2u_i$ that does not intersect the interiors of the other two translates (i=0,1,2). If $K+2u_0$ and $K+2u_2$ are both on the side of ℓ_1 opposite $K+2u_1$, then $\widehat{u_2u_0}$ contains a semicircle, hence $\mu(\widehat{u_2u_0}) \geq \pi$. Thus we assume without loss of generality that $\mu(\widehat{u_2u_0}) < \pi$ and that $K+2u_1$ and $K+2u_2$ are on the same side of ℓ_1 (Figure 2).

Since K touches $K + 2u_1$ and $K + 2u_2$ in u_1 and u_2 , respectively, bd K contains the segment $[u_1, u_2]$. Since $\mu(\widehat{u_2u_0}) < \pi$, we have that $\widehat{u_2u_0}$ is a minor arc, and the separating lines ℓ_0 and ℓ_2 are either parallel or intersect on the same side as u_1 of the line ou_0 . If ℓ_0 and ℓ_2 intersect, then no translate of K can lie in the triangle bounded by ℓ_0, ℓ_1, ℓ_2 . It follows that ℓ_0 and ℓ_2 are parallel and hence $[-u_0, u_2] \subset \operatorname{bd} K$. Therefore, $\mu(-u_0, u_2) = 0$ by definition of π -measure, and we conclude that $\mu(\widehat{u_2u_0}) = \pi$.

Next consider the totally separable packing $\{K, K+2u_0, K+2u_1, K+2(u_1-u_2)\}$. Let ℓ_1 be a line separating K and $K+2u_1$ that does not intersect the interiors of the other two translates. We will say that a translate of K is above (resp., below) ℓ_1 if it lies on the same (resp., opposite) side of ℓ_1 as K. We consider three cases.

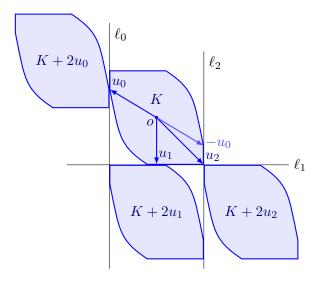


Figure 2: Lemma 19, when $\{K, K + 2u_0, K + 2u_1, K + 2u_2\}$ is a totally separable packing.

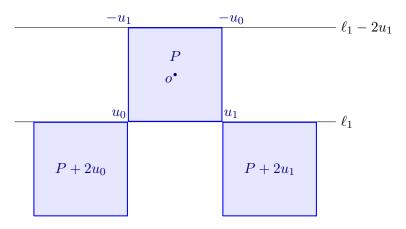


Figure 3: Lemma 19, Case 2

Case 1: Assume that $K + 2u_0$ is above and $K + 2(u_1 - u_2)$ is below ℓ_1 . Then both u_0 and u_2 lie on the side of $\ell_1 - u_1$ opposite to u_1 , hence $\widehat{u_2u_0}$ contains a semicircle, and the claim follows.

Case 2: Assume that $K+2u_0$ is below ℓ_1 . Then $[u_0,u_1]\subset \operatorname{bd} K\cap \ell_1$ and, by Lemma 15, $\|u_1-u_0\|_K>1$. Let P denote the parallelogram $\operatorname{conv}\{\pm u_0,\pm u_1\}$ inscribed to K with $P\neq K$. Moreover, ℓ_1 and ℓ_1-2u_1 are support lines of K. Since no translate of K 'fits between' $P+2u_0$ and $P+2u_1$, it follows that $u_2\in \ell_1-2u_1$ (Figure 3).

Assuming that $\widehat{u_2u_0}$ does not contain a semicircle, the points $-u_1, -u_0, u_2$ follow each other on $\operatorname{bd} K \cap (\ell_1 - 2u_1)$ in this clockwise order. Since $||u_1 - u_0||_K > 1$, we have that $\mu(\widehat{-u_0, u_2}) = 0$ and hence, $\mu(\widehat{u_2u_0}) = \mu(\widehat{-u_0, u_0}) = \pi$ as required.

Case 3: Assume that both $K + 2u_0$ and $K + 2(u_1 - u_2)$ are above ℓ_1 . We can use a very similar argument to the previous case. We have that $[u_2, u_1] \subset \operatorname{bd} K \cap \ell_1$ and, by

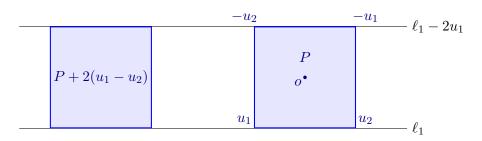


Figure 4: Lemma 19, Case 3

Lemma 15, $||u_2 - u_1||_K > 1$. Let P denote the parallelogram $P = \text{conv}([u_2, u_1] \cup [-u_2, -u_1])$. Clearly, $P \subset K$ with $P \neq K$. Moreover, ℓ_1 and $\ell_1 - 2u_1$ are support lines of K. Since no translate of K 'fits between' P and $P + 2(u_1 - u_2)$, it follows that $u_0 \in \ell_1 - 2u_1$, see Figure 4.

Assuming that $\widehat{u_2u_0}$ does not contain a semicircle, the points $u_0, -u_2, -u_1$ follow each other on $\operatorname{bd} K \cap (\ell_1 - 2u_1)$ in this clockwise order. Since $||u_2 - u_1||_K > 1$, we have that $\widehat{\mu(u_0, -u_2)} = 0$ and hence, $\widehat{\mu(u_2u_0)} = \widehat{\mu(u_2, -u_2)} = \pi$ as required, completing the proof of Lemma 19.

Lemma 19 can now be applied to find a simple derivation of the totally separable Hadwiger numbers of bodies that are not quasi hexagons.

Lemma 20. Let K be a convex body in the plane.

- (i) If K is a parallelogram, then $H_{sep}(K) = 8$.
- (ii) If K is a quasi hexagon but not a parallelogram, then $H_{\text{sep}}(K) = 6$.
- (iii) If K is not a quasi hexagon, then $H_{sep}(K) = 4$.

Proof. It is well known that K is a parallelogram if and only if so is its central symmetral C = (1/2)(K - K). By Lemma 6, K is a quasi hexagon if and only if so is C. Thus, with Lemma 5, we may assume that K is o-symmetric.

It is well known [Grü61] that the Hadwiger number of a parallelogram is 8, and that of any other planar convex body is 6, thus giving the upper bounds in (i) and (ii). The lower bounds are shown by Figure 5.

We prove (iii). First note that any o-symmetric convex body K has a circumscribed parallelogram such that the midpoints of the sides of the parallelogram are on the boundary of K. If we let the midpoints be p_1, p_2, p_3, p_4 , then $\{K\} \cup \{K + 2p_i \mid i = 1, ..., 4\}$ is a totally separable packing, hence $H_{\text{sep}}(K) \geq 4$.

Next we assume that K is not a quasi hexagon, and show that $H_{\text{sep}}(K) \leq 4$. Suppose for a contradiction that $q_0, q_1, \ldots, q_4 \in \text{bd } K$ are unit vectors such that $\{K, 2q_0 + K, \ldots, 2q_4 + K\}$ is a totally separable packing. We may assume that q_0, q_1, \ldots, q_4 are in clockwise order on bd K. Then by Lemma 19, for any π -measure μ on bd K we have $\mu(\widehat{q_iq_{i+2}}) \geq \pi$ for each $i = 0, \ldots, 4$, where subscripts are taken modulo 5. If we add all these angles, we obtain that $2\mu(\text{bd } K) = 5\pi$, a contradiction. This completes the proof of Lemma 20.

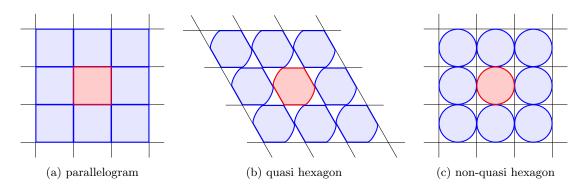


Figure 5: Totally separable packings

Although we will not use it, it can be shown in a similar way that if K is not a quasi hexagon, any two vertices in the contact graph of a totally separable packing of translates of K share at most two neighbors.

4 Proof of Theorem 7

We follow the line of the argument of the proof of [BKO19, Theorem 13], where we use a π -measure on the boundary of a non-quasi hexagon. We also fix a gap in the proof that occurs in the proof of the Euclidean case in [BSS16] which can be traced back to [Har74].

We show the upper bound by induction on n. Let G be the contact graph of a totally separable packing of n translates of K with the maximum number $e = c_{\text{sep}}(K, n)$ of edges. The base cases $n \leq 4$ follow immediately from the fact that G is triangle-free (Lemma 15).

We may assume that G is 2-connected. Indeed, suppose that by the removal of a vertex x, G becomes disconnected. Then G can be decomposed into two subgraphs G_1 and G_2 with only the vertex x in common and with no common edges. Denote the number of vertices of G_i by $n_i \geq 2$, i = 1, 2, where we assume $n_1 \leq n_2$ without loss of generality. Then $n_1 + n_2 = n + 1$, and by the induction hypothesis, the number of edges of G is at most $\lfloor 2n_1 - 2\sqrt{n_1} \rfloor + \lfloor 2n_2 - 2\sqrt{n_2} \rfloor$. It is easy to show that this is at most $\lfloor 2n - 2\sqrt{n} \rfloor$. Indeed, if $4 \leq n_1 \leq n_2$, then by the convexity of the function $t \mapsto 2(t - \sqrt{t})$, we have that $2n_1 - 2\sqrt{n_1} + 2n_2 - 2\sqrt{n_2} \leq 2 \cdot 4 - 2\sqrt{4} + 2(n-3) - 2\sqrt{n-3}$, and this can be checked to be at most $2n - 2\sqrt{n}$ for all $n \geq 4$. If $n_1 = 3 \leq n_2$, then $\lfloor 2n_1 - 2\sqrt{n_1} \rfloor + \lfloor 2n_2 - 2\sqrt{n_2} \rfloor \leq 2 + 2(n-2) - 2\sqrt{n-2} \leq 2n - \sqrt{2n}$. The case $n_1 = 2$ is similar.

We can avoid these calculations by using the fact that in a polyomino with n cells, the number of pairs touching in an edge is at most $\lfloor 2n - \sqrt{2n} \rfloor$ (see [BKO19] and references therein). Consider any polyominoes P_1 and P_2 with exactly $\lfloor 2n_i - 2\sqrt{n_i} \rfloor$ touching cells, respectively. It is then sufficient to translate P_2 so that one of its cells overlaps with a cell of P_1 without there being any other overlaps. This can be done by moving the left-most cell in the top row of P_2 so that it overlaps with the right-most cell in the bottom row of P_1 . This gives a polyomino with n cells and at least $\lfloor 2n_1 - 2\sqrt{n_1} \rfloor + \lfloor n_2 - 2\sqrt{n_2} \rfloor$ cells, which is bounded above by $\lfloor 2n - \sqrt{2n} \rfloor$.

Thus, G is a 2-connected planar graph on n vertices, each of degree 2, 3 or 4 by Lemma 20. Consider the closed polygon P with vertices a_1, \ldots, a_v bounding the outer face of G in counter-clockwise orientation. We will always refer to the indices modulo v. Note that $||a_i - a_{i+1}||_K = 2$ for each i.

We fix a π -measure μ on bd K. Let v_2, v_3 and v_4 denote the number of vertices of degree 2, 3 and 4 of P, where $v_2 + v_3 + v_4 = v$. Each vertex of P is also on some bounded faces of G, and for each such bounded face there is an angle at that vertex. In total, there are $v_2 + 2v_3 + 3v_4$ such angles inside P with vertex on P. We call two such angles adjacent if either they have the same vertex and share an edge, or their vertices are adjacent on P and they share the same bounded face. By Lemma 19, the sum of the μ -measure of two adjacent angles is $\geq \pi$. Thus if we sum up the measures of all adjacent pairs of angles, we obtain a sum of at least $\pi(v_2 + 2v_3 + 3v_4)$. Since each angle blongs to two such pairs, we sum each angle twice. By (1), we obtain $2\pi(v-2) \geq \pi(v_2 + 2v_3 + 3v_4)$. From this we obtain

$$v_2 + 2v_3 + 3v_4 \le 2v - 4. (2)$$

For any positive integer j, denote by g_j the number of internal faces of G with j edges. Since G is triangle-free, $g_1 = g_2 = g_3 = 0$. Since G has $e = c_{\text{sep}}(K, n)$ edges, Euler's formula gives $n - e + g_4 + g_5 + \ldots = 1$. If we add the number of edges bounding the internal faces, then internal edges are counted twice, edges of P are counted once, so we have $4(1 - n + e) = 4(g_4 + g_5 + \ldots) \le 4g_4 + 5g_5 + \ldots = v + 2(e - v)$. This yields

$$e \le 2n - 2 - v/2. \tag{3}$$

If $v \ge 4\sqrt{n} - 4$, then we obtain $e \le 2n - 2\sqrt{n}$, and we are done. Thus we assume without loss of generality that $v < 4\sqrt{n} - 4$. We delete from G the v vertices of P and all edges incident to them. If there is no edge in G that joins two non-adjacent vertices of P (a diagonal), we remove exactly $v_2 + 2v_3 + 3v_4$ edges from P, and we obtain

$$e - (v_2 - 2v_3 + 3v_4) \le 2(n - v) - 2\sqrt{n - v}$$

by the induction hypothesis. Then (2) yields

$$e \le 2n - 4 - 2\sqrt{n - v} < 2n - 4 - 2\sqrt{n - 4\sqrt{n} + 4}$$
$$= 2n - 4 - 2(\sqrt{n} - 2) = 2n - 2\sqrt{n}.$$

To finish the proof of Theorem 7, it remains to consider the case where G has a diagonal. In this case there exist two contact graphs G_1 and G_2 with union G, intersecting in just the diagonal and its two endpoints, such that if G_i has $n_i \geq 4$ vertices and e_i edges (i = 1, 2), then $n_1 + n_2 = n + 2$ and $e_1 + e_2 = e + 1$. By induction we obtain

$$e = e_1 + e_2 - 1 \le 2n_1 - 2\sqrt{n_1} + 2n_2 - 2\sqrt{n_2} - 1 = 2n + 3 - 2(\sqrt{n_1} + \sqrt{n_2})$$

 $\le 2n + 3 - 2(\sqrt{4} + \sqrt{n-2})$ by convexity
 $< 2n - 2\sqrt{n}$ since $n \ge 6$.

We note that the case when G has a diagonal was not treated in [Har74] and subsequently, in [BSS16].

5 Final Remarks

The following problems remain open.

Question 21. In the proof of Proposition 13, we only use $2^{\sqrt{d}}$ separating hyperplanes around each point. Can we modify the ℓ_1^d -unit ball so that it becomes smooth or strictly convex?

Question 22. Can we improve the $2^{d+1}-3$ upper bound for the totally separable Hadwiger number of smooth or strictly convex bodies from [BN18]?

Question 23. What is the smallest dimension d such that there exists a smooth, strictly convex d-dimensional o-symmetric convex body K with H(K) > 2d? We have shown that $d \in \{5, 6, 7, 8\}$. Equivalently, what is the smallest d such that there exists a $(2d+1) \times (2d+1)$ matrix with 1s on the diagonal, all off-diagonal entries in the interval (-1, 0] and rank at most d?

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